

Kloomock and Muffley,^[2] and Raven.^[3] We will follow Kloomock and Muffley's presentation here. Figure 7-8 shows two positions of the follower arm BC being rotated around a "stationary" cam in the typical inversion of the motion for analysis purposes. (Typically, the follower arm pivot B remains stationary and the cam rotates.) The initial position BC becomes $B'C'$ at a later time after the cam has rotated through the angle γ . Though these positions are shown widely separated for clarity, the analysis considers them to be an infinitesimal angle $d\gamma$ apart.

The pressure angle ϕ is defined as the angle between the normal force N applied at the cam-roller interface, shown as vector $C'N$, and the direction of the velocity of the roller center, shown as $C'D'$. Neglecting friction and taking moments about the arm pivot B' gives

$$\frac{Nl}{T} = \frac{1}{\cos\phi} \quad (7.6)$$

where l is the length of the arm and T is the applied load torque on the follower arm. The torque ratio Nl/T is similar to the force magnification factor N/F of equation 7.1b for a radial cam with translating roller follower.

From the geometry of Figure 7-8, note that as $d\gamma$ approaches zero, γ' approaches γ , δ' approaches δ , and ε' approaches ε . An expression for pressure angle ϕ can be written as:

$$\phi = \frac{\pi}{2} - (\varepsilon - \lambda) \quad (7.7a)$$

$$\lambda = \tan^{-1} \frac{1}{R} \frac{dR}{d\gamma} \quad (7.7b)$$

The triangle $OB'C'$ in Figure 7-8a (and shown separately in Figure 7-8b) can be solved for R , ε , and ψ .

$$R = \sqrt{l^2 + c^2 - 2lc \cos\delta} \quad (7.7c)$$

$$\varepsilon = \sin^{-1} \left(\frac{c}{R} \sin\delta \right) \quad (7.7d)$$

$$\psi = \cos^{-1} \left(\frac{c^2 + R^2 - l^2}{2Rc} \right) \quad (7.7e)$$

Also from Figure 7-8 it can be seen that

$$\gamma = \psi_0 - \psi + \theta \quad (7.7f)$$

Differentiating equation 7.7f with respect to R :

$$\frac{d\gamma}{dR} = \frac{d\theta}{dR} - \frac{d\psi}{dR} \quad (7.7g)$$

Differentiating equation 7.7c with respect to θ and reciprocating: